

Supplementary material for the article:

Prekrat, D., Todorovic Vasovic, K. N., Vasović, N., & Kostić, S.. (2024). Complex global dynamics of conditionally stable slopes: effect of initial conditions. in *Frontiers in Earth Science* Frontiers Media., 12 - 2024 <https://doi.org/10.3389/feart.2024.1374942>

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Supplementary Material

1 MEAN-FIELD MODEL

We will here give more details on the derivation of the equation (6). First, let us rewrite the equation of motion (5):

$$dx_i = y_i dt, \quad (\text{S1a})$$

$$dy_i = F(v)dt - F(v + y_i)dt + \sum_{\substack{j=1 \\ j \neq i}}^N \kappa(x_{\tau,j} - x_i)dt + \sqrt{2d} dw_i. \quad (\text{S1b})$$

Since $F(v)$ is cubic in v , its Taylor series terminates with a cubic term

$$F(v + y_i) = F(v) + F'(v)y_i + \frac{1}{2}F''(v)y_i^2 + \frac{1}{6}F'''(v)y_i^3, \quad (\text{S2})$$

yielding

$$dx_i = y_i dt, \quad (\text{S3a})$$

$$dy_i = -((3av^2 - 2bv + c)y_i + (3av - b)y_i^2 + ay_i^3)dt + \sum_{\substack{j=1 \\ j \neq i}}^N \kappa(x_{\tau,j} - x_i)dt + \sqrt{2d} dw_i. \quad (\text{S3b})$$

We will now perform the cumulant analysis of this system of globally coupled units in the thermodynamical limit of an infinitely large $N \rightarrow \infty$ ensemble. Our system now becomes

$$dx_i = y_i dt, \quad (\text{S4a})$$

$$dy_i = -((3av^2 - 2bv + c)y_i + (3av - b)y_i^2 + ay_i^3)dt + N\kappa \cdot \frac{1}{N} \sum_{\substack{j=1 \\ j \neq i}}^N (x_{\tau,j} - x_i)dt + \sqrt{2d} dw_i, \quad (\text{S4b})$$

that is

$$dx_i = y_i dt, \quad (\text{S5a})$$

$$dy_i = -((3av^2 - 2bv + c)y_i + (3av - b)y_i^2 + ay_i^3)dt + k(\langle x_{\tau} \rangle - x_i)dt + \sqrt{2d} dw_i, \quad (\text{S5b})$$

where

$$k = \lim_{\substack{N \rightarrow \infty \\ \kappa \rightarrow 0}} N\kappa. \quad (\text{S6})$$

We will denote all mean field quantities q as

$$\langle q \rangle = \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{j=1}^N q_j, \quad (\text{S7})$$

and for each block element we will introduce deviations from the mean fields

$$n_{x,i} = x_i - \langle x \rangle, \quad n_{y,i} = y_i - \langle y \rangle. \quad (\text{S8})$$

We assume that these fluctuations are Gaussian and statistically independent in the different elements.

There is a set of moments known among physicists as cumulants (Lax et al. (2006), Gardiner (1997)) or among statisticians as Thiele semi-invariants, which have the important property that they all vanish in the Gaussian case. We will introduce the following notation for the first and second order cumulants:

- the means — $m_x = \langle x \rangle, m_y = \langle y \rangle,$
- the variances — $s_x = \langle n_x^2 \rangle, s_y = \langle n_y^2 \rangle,$
- and the cross-cumulant — $u = \langle n_x n_y \rangle.$

From the cumulant analysis, we can determine that

$$\langle y^2 \rangle = s_y + m_y^2, \quad \langle y^3 \rangle = m_y^3 + 3m_y s_y, \quad \langle xy \rangle = u + m_x m_y. \quad (\text{S9})$$

If we apply this to (S5b) and note that the averaging removes the noise term, we get

$$\frac{dm_x}{dt} = m_y, \quad (\text{S10a})$$

$$\begin{aligned} \frac{dm_y}{dt} = & -(3av^2 - 2bv + c)m_y - (3av - b)m_y^2 - am_y^3 \\ & - (3av - b)s_y - 3am_y s_y + k(m_{x,\tau} - m_x). \end{aligned} \quad (\text{S10b})$$

Using the definitions of s_x, s_y and u , (S9) and Itô's chain rule (which is responsible for the reintroduction of d -dependence), it is straightforward, if somewhat laborious, to derive

$$\frac{ds_x}{dt} = 2u; \quad (\text{S11a})$$

$$\frac{ds_y}{dt} = -2s_y[(3av^2 - 2bv + c) + 2(3av - b)m_y + 3a(m_y^2 + s_y)] - 2ku + 2d, \quad (\text{S11b})$$

$$\frac{du}{dt} = -u[(3av^2 - 2bv + c) + 2(3av - b)m_y + 3a(m_y^2 + s_y)] - ks_x + s_y. \quad (\text{S11c})$$

Together, the equations (S10a,b) and (S11a–c) form the system (6), which governs the time evolution of our model:

$$\frac{dm_x}{dt} = m_y, \quad (\text{S12a})$$

$$\begin{aligned} \frac{dm_y}{dt} = & -(3av^2 - 2bv + c)m_y - (3av - b)m_y^2 - am_y^3 \\ & - (3av - b)s_y - 3am_y s_y + k(m_{x,\tau} - m_x), \end{aligned} \quad (\text{S12b})$$

$$\frac{ds_x}{dt} = 2u; \quad (\text{S12c})$$

$$\frac{ds_y}{dt} = -2s_y[(3av^2 - 2bv + c) + 2(3av - b)m_y + 3a(m_y^2 + s_y)] - 2ku + 2d, \quad (\text{S12d})$$

$$\frac{du}{dt} = -u[(3av^2 - 2bv + c) + 2(3av - b)m_y + 3a(m_y^2 + s_y)] - ks_x + s_y. \quad (\text{S12e})$$

REFERENCES

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